

5.5 Complex Eigenvalues

Consider $R = \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix}$ which is a rotation and scaling matrix. Find λ such that $R\vec{x} = \lambda\vec{x}$.

$$\det(R - \lambda I) = 0 \Rightarrow \det \begin{bmatrix} 1-\lambda & -1 \\ 1 & 1-\lambda \end{bmatrix} = 0$$

$$(1-\lambda)(1-\lambda) + 1 = 0$$

$$\lambda^2 - 2\lambda + 2 = 0$$

$$\lambda = \frac{2 \pm \sqrt{4 - 4 \cdot 1 \cdot 2}}{2} = 1 \pm \frac{\sqrt{-4}}{2} = 1 \pm \frac{2i}{2} = 1 \pm i$$

$$\lambda = 1 \pm i$$

Eigen values of real matrices will always occur in conjugate pairs (Fund. Thm of Algebra)

Now, find eigenvectors:

$$\lambda = 1+i: \quad (R - \lambda I)\vec{x} = \vec{0}$$

$$\begin{bmatrix} 1-(1+i) & -1 \\ 1 & 1-(1+i) \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \vec{0}$$

$$\begin{bmatrix} -i & -1 \\ 1 & -i \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$-ix_1 - x_2 = 0 \quad \text{and} \quad x_1 - ix_2 = 0$$

$$\text{Choose } x_1 = ix_2 \text{ so } x_2 = 1 \rightarrow x_1 = i$$

$$\vec{x} = \begin{bmatrix} i \\ 1 \end{bmatrix}$$

(any scalar multiple works as well)

We can find $\vec{x}$ corresponding to $\lambda = 1-i$ in the same way, or note the following when A is a real matrix

$$A\vec{x} = \lambda\vec{x}$$

$$\overline{A\vec{x}} = \overline{\lambda\vec{x}}$$

$$\overline{A}\overline{\vec{x}} = \overline{\lambda}\overline{\vec{x}}$$

$$A\overline{\vec{x}} = \overline{\lambda}\overline{\vec{x}}$$

so if λ is a complex eigenvalue of A with $\vec{x}$ its associated eigenvector, then $\overline{\lambda}$ is also an eigenvalue and $\overline{\vec{x}}$ is the corresponding eigenvector

$$\text{so } \lambda = 1+i \quad \vec{x} = \begin{bmatrix} i \\ 1 \end{bmatrix}$$

$$\lambda = 1-i \quad \vec{x} = \begin{bmatrix} -i \\ 1 \end{bmatrix}$$

We will use $\text{Re } \vec{x}$ to denote the real part of $\vec{x}$ if $\vec{x}$ has complex entries. Similarly $\text{Im } \vec{x}$ is the imaginary part.

$$\vec{x} = \text{Re } \vec{x} + i \text{Im } \vec{x}$$

$$\vec{x} = \begin{bmatrix} 3+i \\ 4 \end{bmatrix} \quad \text{Re } \vec{x} = \begin{bmatrix} 3 \\ 4 \end{bmatrix} \quad \text{Im } \vec{x} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

Find eigenvectors of $\begin{bmatrix} a & -b \\ b & a \end{bmatrix}$

$$\det \begin{bmatrix} a-\lambda & -b \\ b & a-\lambda \end{bmatrix} = 0 \Rightarrow (a-\lambda)^2 + b^2 = 0$$

$$\lambda^2 - 2a\lambda + a^2 + b^2 = 0$$

$$\lambda = \frac{2a \pm \sqrt{4a^2 - 4(a^2 + b^2)}}{2}$$

$$= a \pm \frac{\sqrt{-4b^2}}{2}$$

$$= a \pm \frac{2bi}{2}$$

$$= a \pm bi$$

Interesting!

Thm Let A be a 2×2 real matrix with a complex eigenvalue $\lambda = a - ib$ and associated eigenvector $\vec{v} \in \mathbb{C}^2$. Then

$$A = PCP^{-1}, \quad P = [\operatorname{Re} \vec{v} \quad \operatorname{Im} \vec{v}], \quad C = \begin{bmatrix} a & -b \\ b & a \end{bmatrix}$$

This shows that multiplication by a 2×2 matrix with complex eigenvalues always produces a rotation.

$$\text{Since } A = PCP^{-1}, \quad A\vec{x} = P[C[P^{-1}\vec{x}]]$$

$\uparrow$ change variables
 $\uparrow$ rotate and scale
 $\uparrow$ change back to original variables

Proof: First we note two things

$$\begin{aligned} \textcircled{1} \quad A\vec{v} &= A(\operatorname{Re}\vec{v} + i\operatorname{Im}\vec{v}) \\ &= A\operatorname{Re}\vec{v} + iA\operatorname{Im}\vec{v} \end{aligned}$$

so

$$\operatorname{Re} A\vec{v} = A\operatorname{Re}\vec{v} \quad \text{and} \quad \operatorname{Im} A\vec{v} = A\operatorname{Im}\vec{v}$$

$$\textcircled{2} \quad (a-ib)\vec{v} = (a-ib)(\operatorname{Re}\vec{v} + i\operatorname{Im}\vec{v}) = \underbrace{a\operatorname{Re}\vec{v} + b\operatorname{Im}\vec{v}}_{\operatorname{Re}} + i \underbrace{(a\operatorname{Im}\vec{v} - b\operatorname{Re}\vec{v})}_{\operatorname{Im}}$$

Now the proof: Since we want to show $A = PCP^{-1}$ it is enough to show $AP = PC$ and that P is invertible.

$$\begin{aligned} AP &= A[\operatorname{Re}\vec{v} \quad \operatorname{Im}\vec{v}] \\ &= [A\operatorname{Re}\vec{v} \quad A\operatorname{Im}\vec{v}] \\ &= [\operatorname{Re} A\vec{v} \quad \operatorname{Im} A\vec{v}] \quad \text{by } \textcircled{1} \\ &= [\operatorname{Re}(a-ib)\vec{v} \quad \operatorname{Im}(a-ib)\vec{v}] \quad \text{since } a-ib \text{ is an eigenvalue of } A \\ &= [a\operatorname{Re}\vec{v} + b\operatorname{Im}\vec{v} \quad a\operatorname{Im}\vec{v} - b\operatorname{Re}\vec{v}] \quad \text{by } \textcircled{2} \\ &= [\operatorname{Re}\vec{v} \quad \operatorname{Im}\vec{v}] \begin{bmatrix} a & -b \\ b & a \end{bmatrix} \\ &= PC \end{aligned}$$

How do we know P is invertible?

Ex Find P & C such that $A = PCP^{-1}$ if $A = \begin{bmatrix} 5 & -2 \\ 1 & 3 \end{bmatrix}$

$$0 = \det(A - \lambda I) = \det \begin{bmatrix} 5-\lambda & -2 \\ 1 & 3-\lambda \end{bmatrix} = (5-\lambda)(3-\lambda) + 2$$

$$= 15 - 8\lambda + \lambda^2 + 2$$

$$0 = \lambda^2 - 8\lambda + 17$$

$$\lambda = \frac{8 \pm \sqrt{64 - 4 \cdot 17}}{2} = \frac{8 \pm i2}{2} = 4 \pm i$$

$$\text{So } \lambda = a - ib = 4 - i.$$

$$(A - \lambda I) \vec{x} = \vec{0} \Rightarrow \begin{bmatrix} 5-(4-i) & -2 \\ 1 & 3-(4-i) \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$(1+i)x_1 - 2x_2 = 0$$

$$x_1 + (-1+i)x_2 = 0$$

$$\text{if } x_2 = 1 \text{ then } (1+i)x_1 = 2 \rightarrow x_1 = 1-i$$

So

$$\vec{v} = \begin{bmatrix} 1-i \\ 1 \end{bmatrix}$$

$$\text{Re } \vec{v} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$\text{Im } \vec{v} = \begin{bmatrix} -1 \\ 0 \end{bmatrix}$$

$$\therefore \boxed{P = \begin{bmatrix} 1 & -1 \\ 1 & 0 \end{bmatrix} \quad C = \begin{bmatrix} 4 & -1 \\ 1 & 4 \end{bmatrix}}$$

check $AP = PC$

$$AP = \begin{bmatrix} 5 & -2 \\ 1 & 3 \end{bmatrix} \begin{bmatrix} 1 & -1 \\ 1 & 0 \end{bmatrix} = \begin{bmatrix} 3 & -5 \\ 4 & -1 \end{bmatrix}$$

$$PC = \begin{bmatrix} 1 & -1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 4 & -1 \\ 1 & 4 \end{bmatrix} = \begin{bmatrix} 3 & -5 \\ 4 & -1 \end{bmatrix}$$

same ✓